

DIAGONAL ARGUMENTS AND LAWVERE'S THEOREM

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ABSTRACT. Overview of the Lawvere's fixed point theorem and some of its applications.

CATEGORY THEORY

Categories. A *category* \mathcal{C} is a collection of *objects* \mathcal{C}_0 and *arrows* \mathcal{C}_1 , such that each arrow $f \in \mathcal{C}_1$ has a *domain* and a *codomain*, both objects \mathcal{C}_0 . We write $f : A \rightarrow B$ for an arrow $f \in \mathcal{C}_1$ with a domain $A \in \mathcal{C}_0$ and a codomain $B \in \mathcal{C}_0$.

Given two arrows $f : A \rightarrow B$ and $g : B \rightarrow C$, we can *compose* them, to obtain an arrow $g \circ f = gf : A \rightarrow C$.

$$\begin{array}{ccccc}
 A & \xrightarrow{f} & B & \xrightarrow{g} & C \\
 & & \searrow & \nearrow & \\
 & & & gf &
 \end{array}$$

The composition operation, when defined, is associative, i.e. $h(gf) = (hg)f$. We additionally require for each object $A \in \mathcal{C}_0$ an arrow $\text{id}_A : A \rightarrow A$ that is an identity element: $\text{id}_B \circ f = f \circ \text{id}_A = f$ for any $f : A \rightarrow B$.

By $\text{Hom}_{\mathcal{C}}(A, B)$ we denote a collection of arrows with a domain A and a codomain B .

Example 1. Some prominent categories: **Set**, a category of sets and functions between them; **Grp**, a category of groups and group homomorphisms; a trivial category **1** consisting of one object and one identity arrow. The last example can be generalized as follows: pick a poset (P, \leq) , it induces a category with objects elements of P . The set $\text{Hom}_P(a, b)$ contains exactly one arrow if $a \leq b$, and $\text{Hom}_P(a, b) = \emptyset$ otherwise.

Finite products. We say that a category \mathcal{C} has *binary products* if for every pair of objects $A, B \in \mathcal{C}_0$ there is an object $A \times B$ and arrows $\pi_1 : A \times B \rightarrow A, \pi_2 : A \times B \rightarrow B$ such that for any two arrows $f : X \rightarrow A, g : X \rightarrow B$ there is a unique arrow $\langle f, g \rangle : X \rightarrow A \times B$ such that $\pi_1 \circ \langle f, g \rangle = f$ and $\pi_2 \circ \langle f, g \rangle = g$ (see the diagram below on the left).

$$\begin{array}{ccccc}
 & & X & & X \\
 & f \swarrow & \downarrow \langle f, g \rangle & \searrow g & \vdots \\
 A & \xleftarrow{\pi_1} & A \times B & \xrightarrow{\pi_2} & B & \downarrow \\
 & & & & & 1
 \end{array}$$

The definition of binary products can be generalized to n -ary products for any finite n . In case $n = 0$ we speak of a *terminal object* 1 , with the following property (see the diagram on the right above): for each object X there is a unique arrow $X \rightarrow 1$.

Example 2. In **Set**, a product $A \times B$ is just a cartesian product of two sets. The terminal object is then a one-element set $1 = \{*\}$.

LAWVERE'S DIAGONAL ARGUMENT

Generalizing from the example of sets, we call maps $1 \rightarrow X$ *global elements* of X . In **Set** such functions precisely correspond to members of X .

We can then state when some arrow $f : A \rightarrow B$ behaves like a “surjection” on global elements.

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Definition 3. An arrow $f : A \rightarrow B$ is *point-surjective* if for every global element $b : 1 \rightarrow B$ there is a global element $a : 1 \rightarrow A$ such that $f \circ a = b$.

Equivalently, $\text{Hom}(1, f) : \text{Hom}(1, A) \rightarrow \text{Hom}(1, B)$ is surjective.

Some categories with products support “function spaces”: objects B^A , which somehow internalize arrows $A \rightarrow B$ (in **Set**: a collection of arrows $\text{Hom}(A, B)$ between sets is itself a set). For such a function space we can weaken the notion of point-surjectivity, requiring that an element of the preimage of some function g is only *extensionally* equal to g . Luckily, we can state this property without mentioning categorical exponents.

Definition 4. An arrow $f : X \times A \rightarrow Y$ is *weakly point-surjective* if for every arrow $g : X \rightarrow Y$ there is a global element $a : 1 \rightarrow A$ such that for all $x : 1 \rightarrow X$, $f \circ \langle x, a \rangle = g \circ x$:

$$\forall g \exists a \forall x (f \langle x, a \rangle = gx)$$

One can think of such f as a series of functions $f \langle -, a \rangle$ such that for each $g : X \rightarrow Y$ there is a function $f \langle -, a \rangle$ which is extensionally equal to g .

Theorem 5 (Lawvere). Suppose that $f : A \times A \rightarrow B$ is weakly point-surjective. Then every map $t : B \rightarrow B$ has a fixed point, i.e. an element $x : 1 \rightarrow B$ such that $tx = x$.

Proof. Consider a composite $t \circ f \circ \langle \text{id}_A, \text{id}_A \rangle : A \rightarrow B$.

$$\begin{array}{ccc} A \times A & \xrightarrow{f} & B \\ \Delta \uparrow & & \downarrow t \\ A & \xrightarrow{t \circ f \circ \Delta} & B \end{array}$$

By the assumption, there is a global element $a : 1 \rightarrow A$ such that

$$\forall (x : 1 \rightarrow A). (f \langle x, a \rangle = t \circ f \circ \langle \text{id}_A, \text{id}_A \rangle \circ x = t(f \langle x, a \rangle))$$

In particular, for $x = a$: $f \langle a, a \rangle = t(f \langle a, a \rangle)$. Hence, $f \langle a, a \rangle$ is a fixed point of t . \square

Corollary 6. Suppose that a map $\neg : \Omega \rightarrow \Omega$ doesn’t have a fixed point. Then there is no weakly point-surjective map $A \rightarrow \Omega^A$ for any A .

Then we can obtain Cantor’s theorem in a straightforward way: since the negation map $\neg : 2 \rightarrow 2$ has a fixed-point, there is not surjective map $A \rightarrow 2^A = \mathcal{P}(A)$. By substituting Ω for 2 we obtain Cantor’s theorem in an arbitrary (non-degenerate) topos.

RUSSEL’S PARADOX AND UNBOUNDED COMPREHENSION

Suppose there is a set-theoretic universe $\mathcal{U} \in \mathbf{Set}$, a “set of all sets”. To recover Russel’s paradox we consider a relation $\epsilon : \mathcal{U} \times \mathcal{U} \rightarrow 2$ where $\epsilon(x, y) = 1 \iff x \in y$, and take the negation of the diagonal of ϵ :

$$\begin{array}{ccc} \mathcal{U} \times \mathcal{U} & \xrightarrow{\epsilon} & 2 \\ \Delta \uparrow & & \downarrow \neg \\ \mathcal{U} & \xrightarrow{\neg \circ \epsilon \circ \Delta} & 2 \end{array}$$

The composite $\neg \circ \epsilon \circ \Delta$ is a map $\mathcal{U} \rightarrow 2$, that is, a predicate on \mathcal{U} that is **true** on the sets x for which $\neg(x \in x)$ holds; i.e. for sets that do not contain themselves. Now, for obtaining Russel’s paradox we would have to show that ϵ is weakly-point surjective. What does it mean for \mathcal{U} specifically? It would mean that for any predicate $\phi : \mathcal{U} \rightarrow 2$ on sets there exists a set $x \in \mathcal{U}$ (corresponding to a map $x : 1 \rightarrow \mathcal{U}$) such that the members of x are exactly such sets that satisfy ϕ :

$$\frac{\phi : \mathcal{U} \rightarrow 2}{\exists x \in \mathcal{U} \forall y \in \mathcal{U} (y \in x = \phi(y))}$$

This rule is exactly the *unbounded comprehension scheme* for \mathcal{U} ! As you can see, employing Lawvere's analysis for this paradox pinpoints exactly to the problematic part: the unbounded comprehension schema for \mathcal{U} . Restricting the comprehension schema to already-defined sets is exactly the fix that was utilized in axiomatic set theory. Notice that this analysis shows that the issue does not lie in self-reference or the size of \mathcal{U} per se. After all, the universe \mathcal{U} does not have to contain “all” sets; we can replace the word “set” in the previous paragraph by “ \mathcal{U} -set” and the argument would still go through.

LINDENBAUM-TARSKI CATEGORIES AND INCOMPLETENESS

Consider a first-order theory \mathbb{T} . We form $\mathcal{C}(\mathbb{T})$ a *classifying category* of \mathbb{T} in the following way: objects of $\mathcal{C}(\mathbb{T})$ are generated by a sort object A (more object if the theory is multi-sorted), and a dummy object 2 , by closure under products. Thus, the objects of \mathbb{T} are of the form $A^n \times 2^m$. A map $\varphi : A^n \rightarrow 2$ is an equivalence class of provably equivalent formulas φ of n variables. A map $A^n \rightarrow 2 \times 2$ is a tuple of formulas of n free variables, and so on. A map $t : A^n \rightarrow A$ is a class of provably equal terms with n free variables. In particular, maps $1 \rightarrow 2$ are *sentences* of \mathbb{T} , and maps $1 \rightarrow A$ are definable constants/terms of \mathbb{T} .

A theory is *consistent* if the collection of maps $1 \rightarrow 2$ contains at least two elements **true**, **false**, corresponding to statements that are provable in the theory, and statements that are refutable in the theory. A theory is *complete* if the collection of maps $1 \rightarrow 2$ is exactly $\{\mathbf{true}, \mathbf{false}\}$, i.e. every sentence is either provable or refutable.

Undefinability of sat. Suppose that the satisfiability predicate is definable in \mathbb{T} :

$$\vdash \text{sat}(a, \ulcorner \varphi \urcorner) \leftrightarrow \varphi(a)$$

for all φ, a .

In categorical terms, we have a Gödel encoding, $\ulcorner - \urcorner : \text{Hom}(A^n, 2) \rightarrow \text{Hom}(1, A)$, and a formula $\text{sat} : A \times A \rightarrow 2$, such that for any $\varphi : A \rightarrow 2$, and for all $a : 1 \rightarrow A$, $\text{sat}(a, \ulcorner \varphi \urcorner) = \varphi a$. But this is exactly the condition for weak point-surjectivity! Hence, every function $2 \rightarrow 2$ has a fixed point, and we are in an inconsistent theory.

Undefinability of truth. We say that truth is definable in a theory, if there is a formula T , such that

$$\vdash T(\ulcorner \varphi \urcorner) \leftrightarrow \varphi$$

So it is very much like **sat**, but only for sentences. Categorically, we can say that $T : A \rightarrow 2$ is a truth predicate, if $\text{Hom}(1, T) : \text{Hom}(1, A) \rightarrow \text{Hom}(1, 2)$ is a retract of $\ulcorner - \urcorner : \text{Hom}(1, 2) \rightarrow \text{Hom}(1, A)$; or, $T \circ \ulcorner \varphi \urcorner = \varphi$. So, suppose that \mathbb{T} has a truth predicate, and suppose further that it supports “substitution”:

$$\mathbb{T} \vdash \text{subst}(a, \ulcorner \varphi \urcorner) = \ulcorner \varphi(a) \urcorner$$

In that case, we can define **sat** as the composite $T \circ \text{subst}$.

Incompleteness. A provability predicate is a predicate P such that

$$\mathbb{T} \vdash P(\ulcorner \varphi \urcorner) \quad \text{iff} \quad \mathbb{T} \vdash \varphi$$

In categorical terms, $P \circ \ulcorner \varphi \urcorner = \varphi$ given that both $P \circ \ulcorner \varphi \urcorner$ and φ take value in $\{\mathbf{true}, \mathbf{false}\}$. But if \mathbb{T} is complete, then the provability predicate is also a truth predicate.

ASSEMBLIES AND THE HALTING PROBLEM

Consider the category Asm of *assemblies*. The objects are pairs (X, \Vdash_X) where $X \in \mathbf{Set}$ and $\Vdash_X \subseteq \mathbb{N} \times X$ such that for each $x \in X$ there is at least one number $n \Vdash_X x$. Elements m such that $m \Vdash_X x$ are called *realizers* of x and we say that m *realizes* x . A map $f : (X, \Vdash_X) \rightarrow (Y, \Vdash_Y)$ is a morphism of assemblies if there is a partial computable function ϕ such that whenever $n \Vdash_X x$, $\phi(n)$ terminates and $\phi(n) \Vdash_Y f(x)$. We say that ϕ *tracks* or *realizes* f . The products in Asm are given by surjective pairings. There is a natural numbers object \mathbf{N} in Asm given by $(\mathbb{N}, \Vdash_{\mathbf{N}})$ where $n \Vdash_{\mathbf{N}} m$ iff $n = m$.

Proposition 7. The morphisms $\mathbf{N} \rightarrow \mathbf{N}$ are exactly (total) computable functions.

Definition 8. Asm has all finite types. For instance, the object 2 is given by $(\{0, 1\}, \Vdash_2)$ where $i \Vdash_2 j$ iff $i = j$.

Suppose that the halting problem is decidable. We define a morphism $halt : \mathbf{N} \times \mathbf{N} \rightarrow 2$ such that $halt(n, m) = 1$ iff the partial computable function $\{n\}(-) : \mathbb{N} \rightarrow \mathbb{N}$ terminates on the input m . For $halt$ to be weak point-surjective we must show that for any morphism $f : \mathbf{N} \rightarrow 2$ there is a number n such that $halt(n, m) = f(m)$ for all m , i.e. $\{n\}(m)$ terminates iff $f(m) = 1$. How do we construct such n ? Well, f is tracked by some computable ϕ , so n is just the Gödel code of an algorithm/function that runs $\phi(m)$ on input m and terminates if the output of $\phi(m)$ is 1, and diverges otherwise.

OBTAINING FIXED POINTS

Retractions & the Y -combinator. An epimorphism $r : E \rightarrow B$ is said to be *split*, if there is a map $s : B \rightarrow E$ in the opposite direction such that $r \circ s = \text{id}_B$. This is equivalent to saying that $Hom(A, r) : Hom(A, E) \rightarrow Hom(A, B)$ is surjective for all A . Clearly, any split epimorphism is point-surjective, the choice for the witness for the existential quantifier is given by s . (However, not every epimorphism is point-surjective, and not every point-surjective map is epi)

Consider the category CPO_{\perp} of direct-complete partial orders with \perp . It is a cartesian closed category with a *reflexive* element U ; that is an object $U \neq 1$ such that there is a retraction $r : U \rightarrow U^U$. Such a domain U provides a model for untyped λ -calculus; furthermore, a complete class of models of λ -calculus arises in such a way: see section 5.5 in Barendregt's book.

Anyway, what follows is that every map $t : U \rightarrow U$ has a fixed point; this fixed point is exactly the one given by the Y -combinator!

By computation, a fixed point of t is given by $\bar{r} \circ \Delta \circ s(\overline{t \circ \bar{r} \circ \Delta})$. Mixing syntax and semantics informally we have $\bar{r} \circ \langle a, b \rangle = ab$ and $s(x \mapsto g(x)) = \lambda x. g(x)$, so the fixed point is

$$(\overline{s(\overline{t \circ \bar{r} \circ \Delta})})(\overline{s(\overline{t \circ \bar{r} \circ \Delta})}) = (\lambda x. (t \circ \bar{r} \circ \langle x, x \rangle))(\lambda x. (t \circ \bar{r} \circ \langle x, x \rangle)) = (\lambda x. (t(xx)))(\lambda x. (t(xx)))$$

which is exactly $Y(t)$.

Enumerations of r.e. sets. Consider an assembly $\Sigma \in Asm$ defined as an underlying set $\{\top, \perp\}$ with the realizability relation

$$n \Vdash \top \iff \{n\}(n) \downarrow \quad n \Vdash \perp \iff \{n\}(n) \uparrow$$

Such Σ is called a *r.e. subobject classifier* or a *r.e. dominance*.

Morphisms $X : \mathbf{N} \rightarrow \Sigma$ are recursively-enumerable sets. Given a map $X : \mathbf{N} \rightarrow \Sigma$ tracked by ϕ we define a set $\bar{X} = \{x \in \mathbb{N} \mid X(x) = \top\}$. To check that $n \in \bar{X}$ we attempt to compute $\{\phi(n)\}(\phi(n))$. If $\{\phi(n)\}(\phi(n))$ terminates, then $n \in \bar{X}$. Similarly, given a r.e. set Y we put $\bar{Y}(n) = \top \iff (n \in Y)$; \bar{Y} is then tracked by a computable function that sends n to the Gödel code of the decision procedure $x \mapsto [n \in Y]$.

The exponent $\Sigma^{\mathbf{N}}$ is then the collection of r.e. sets. We know that there is an enumeration of r.e. sets, thus a weakly point-surjective $W : \mathbf{N} \rightarrow \Sigma^{\mathbf{N}}$. Hence, by Lawvere's theorem every map $\Sigma \rightarrow \Sigma$ has a fixed point. It immediately follows that negation is not definable on Σ and hence r.e. sets are not closed under complements.

Note that $\Sigma^{\mathbf{N}} \simeq \Sigma^{\mathbf{N} \times \mathbf{N}} \simeq \Sigma^{\mathbf{N}^{\mathbf{N}}}$, so every map $\Sigma^{\mathbf{N}} \rightarrow \Sigma^{\mathbf{N}}$ has a fixed point as well. We can identify the exponent $\Sigma^{\mathbf{N}}$ with an assembly (RE, W) where RE is the set of r.e. subsets of \mathbf{N} and $W(A) = \{e \mid A = W_e\}$ for an enumeration $\{W_i\}_i$ of r.e. sets.

A map $F : (RE, W) \rightarrow (RE, W)$ is an enumeration operator: $F(W_e) = W_{\phi(e)}$, for some computable ϕ . The Lawvere's argument states that every such operator has a fixed point: $W_k = W_{\phi(k)}$. Consider a computable ϕ which for every n outputs the r.e. index (todo: is that the term?) of a r.e. set that is just a singleton $\{n\}$, that is $W_{\phi(n)} = \{n\}$. By the existence of a fixed point we have a number k such that $W_k = \{k\}$.

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APPENDIX

We would like to make a few additional remarks.

Remark 9. A finer analysis of the argument might reveal the following fact: it is not necessary to take the diagonal map $\Delta : A \rightarrow A \times A$. One can easily take any other map $\langle \text{id}_A, k \rangle$ for a “good” $k : A \rightarrow A$ (say, if k is an isomorphism). Then the fixed-point for a map $t : B \rightarrow B$ can be constructed from

$$t(f\langle x, k(x) \rangle) = f\langle x, b \rangle$$

If k is an isomorphism, then we can find such x that $k(x) = b$. Then we obtain the fixed point in a similar manner.