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Finitary Higher Inductive Types in the Groupoid Model

Sections 1-3

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Outline

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Problem Set-Up

Recall.. Martin-Löf introduced $\mathbf{I}(A, a, a')$

- Elements of $\mathbf{I}(A, a, a')$ are proofs that a and a' are equal elements of A .
- Can obtain an infinite tower of higher identity types:

$$\begin{aligned} & A \\ & \mathbf{I}(A, a, a') \\ & \mathbf{I}(\mathbf{I}(A, a, a'), p, p') \\ & \mathbf{I}(\mathbf{I}(\mathbf{I}(A, a, a'), p, p'), \theta, \theta') \\ & \dots \end{aligned}$$

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– Collapses in extensional type theory. Why?

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..infinite tower of higher identity types:

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Works in **intensional type theory**.

- Proved by Hofmann and Streicher using the groupoid model.

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Higher Inductive Types (HIT)

Definition

A **higher inductive type** is a type in which all the iterated identity types are generated inductively.

Examples:

- 1-hit: $I(A, a, a')$
- 2-hit: $I(I(A, a, a'), p, p')$

Has a topological interpretation:

- a and a' are points in space;
- p and p' are paths from from a to a' ;
- θ and θ' are homotopies between p and p' .

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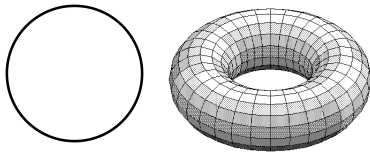
Higher Inductive Types: Examples

Circle is a 1-hit.

```
Inductive circle : Type :=  
| base : circle  
| loop : base == base.
```

Torus is a 2-hit (next presentation).

- 2-path represents the surface that commutes meridional and longitudinal loops.



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Problem

Formalisation of syntax and semantics is still lacking.

Want to formulate a general theory of higher inductive types:

- 1 Represent CL as a 1-HIT.
- 2 Determine general schema for point and path constructors;
- 3 Construct the elimination and equality rules;



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Function Types

- *Dependent function types:* $(x : A) \rightarrow B(x)$
- *Non-dependent function types:* $A \rightarrow B$

Identity Types

$a =_A a'$ (preferred notation) instead of $I(A, a, a')$

Function Application

- If $x : A \vdash C$, then we write $C(x)$ to emphasize dependence.
- Write $C(a)$ to denote substituting a for x in C .



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Introduction Rule

$$\text{refl} : (x : A) \rightarrow x =_A x$$

Elimination Rule (Induction Principle)

$$J_C : (x : A) \rightarrow C(x, \text{refl}(x)) \rightarrow (y : A) \rightarrow (z : x =_A y) \rightarrow C(y, z)$$

where $x : A, y : A, z : x =_A y \vdash C(y, z)$.

Equality Rule

$$J_C(x, d, x, \text{refl}(x)) = d$$



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Heterogeneous Identity Type

$a =_p^B a'$ compares $a : B(x)$ and $a' : B(x')$ where $p : x =_A x'$

Identity Preservation

$$\mathbf{apd}_f : (p : x =_A x') \rightarrow f(x) =_p^B f(x')$$



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Examples

- examples of combinators: S, I and K
- as 1-hit: CL is a type

$$Kxy = x$$

$$Ix = x$$

$$Sxyz = xz(yz)$$



Introduction Rules

Point Constructors

$K, S : CL$ and $\mathbf{app} : CL \rightarrow CL \rightarrow CL$

Path Constructors

- $K_{conv} : (x, y : CL) \rightarrow \mathbf{app}(\mathbf{app}(K, x), y) =_{CL} x$
- $S_{conv} : (x, y, z : CL) \rightarrow \mathbf{app}(\mathbf{app}(\mathbf{app}(S, x), y), z) =_{CL} \mathbf{app}(\mathbf{app}(x, z), \mathbf{app}(y, z))$

Properties Derived from $=_{CL}$

- Reflexivity
- Transitivity
- Symmetry
- Application preserves equality

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Elimination Rules

Assumptions

- $\tilde{K} : C(K)$
- $\tilde{S} : C(S)$
- $\mathbf{a\tilde{p}p} : (x : CL) \rightarrow C(x) \rightarrow (y : CL) \rightarrow C(y) \rightarrow C(\mathbf{app}(x, y))$

Path Assumptions

- $\tilde{K}_{conv} : (x, y : CL) \rightarrow (\tilde{x} : C(x)) \rightarrow (\tilde{y} : C(y)) \rightarrow \mathbf{a\tilde{p}p}(\mathbf{app}(K, x), \mathbf{a\tilde{p}p}(K, \tilde{K}, x, \tilde{x}), y, \tilde{y}) =_{\tilde{K}_{conv}(x, y)}^C \tilde{x}$
- Analogous for \tilde{S}_{conv}

Result

$$f : (x : CL) \rightarrow C(x)$$

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Path Assumptions

- $\tilde{K}_{conv} : (x, y : CL) \rightarrow (\tilde{x} : C(x)) \rightarrow (\tilde{y} : C(y)) \rightarrow \mathbf{app}(\mathbf{app}(K, x), \mathbf{app}(K, \tilde{K}, x, \tilde{x}), y, \tilde{y}) =_{\tilde{K}_{conv}(x, y)}^C \tilde{x}$
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Path Assumptions

- $\tilde{K}_{conv} : (x, y : CL) \rightarrow (\tilde{x} : C(x)) \rightarrow (\tilde{y} : C(y)) \rightarrow \mathbf{app}(\mathbf{app}(K, x), \mathbf{app}(K, \tilde{K}, x, \tilde{x}), y, \tilde{y}) =_{\tilde{K}_{conv}(x, y)}^C \tilde{x}$
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Function Equality

- $f(K) = \tilde{K}$
- $f(S) = \tilde{S}$
- $f(\mathbf{app}(x, y)) = \mathbf{app}(x, f(x), y, f(y))$

Path Equality

- $\mathbf{apd}_f(K_{conv}(x, y)) = \tilde{K}_{conv}(x, y, f(x), f(y))$
- $\mathbf{apd}_f(S_{conv}(x, y, z)) = \tilde{S}_{conv}(x, y, z, f(x), f(y), f(z))$



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Setoids

Idea: dependent type theory with $(x : A) \rightarrow B(x)$, $a =_A a'$, and CL, has a setoid model.

Definition

A **setoid** is a set S equipped with an equivalence relation R .

- Intuitively, can be thought of as a set where elements are considered equivalent under a given relation.

Examples are:

- Modulo arithmetic: $(\mathbb{Z}, \equiv \text{ mod } n)$
- Rational numbers: $(a, b) \sim (c, d) \iff ad = bc$

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Examples

- 1 Interpret **type as a setoid** A , consisting of a set A_0 together with an equivalence relation R .
 - R is represented as a binary family of sets $(A_1(x, x'))_{x, x' \in A_0}$ such that $A_1(x, x')$ is inhabited $\iff R(x, x')$ holds.
- 2 CL is a setoid (CL_0, CL_1) where CL_0 is an inductive type generated by K, S and **app** and CL_1 is an inductive family generated by K_{conv} and S_{conv} and the constructors for transitivity, reflexivity, symmetry and preservation of equality by **app**.



Constructing a General Schema

Use the schema in the style of inductive families:

- point constructor \leftarrow constructor for an inductive type
- path constructor \leftarrow constructor for a binary inductive family

General form for an inductive type \mathbf{H} :

$$\begin{aligned} & (x_1 : A_1) \rightarrow \cdots \rightarrow (x_m : A_m(x_1, \dots, x_{m-1})) \\ & \rightarrow (B_1(x_1, \dots, x_m) \rightarrow \mathbf{H}) \rightarrow \cdots \\ & \rightarrow (B_n(x_1, \dots, x_m) \rightarrow \mathbf{H}) \rightarrow \mathbf{H} \end{aligned}$$

- $A_m(x_1, \dots, x_{m-1})$ is a type if $(x_1 : A_1, \dots, x_{m-1} : A_{m-1}(x_1, \dots, x_{m-2}))$;
- $B_1(\dots)$ and $B_n(\dots)$ are types if $(x_1 : A_1, \dots, x_m : A_m(x_1, \dots, x_{m-1}))$.
- A_i and B_j do not depend on \mathbf{H} .

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Constructing a General Schema

Use the schema in the style of inductive families:

- point constructor \leftarrow constructor for an inductive type
- path constructor \leftarrow constructor for a binary inductive family

General form for an inductive type \mathbf{H} :

$$\begin{aligned} & (x_1 : A_1) \rightarrow \cdots \rightarrow (x_m : A_m(x_1, \dots, x_{m-1})) \\ & \rightarrow (B_1(x_1, \dots, x_m) \rightarrow \mathbf{H}) \rightarrow \cdots \\ & \rightarrow (B_n(x_1, \dots, x_m) \rightarrow \mathbf{H}) \rightarrow \mathbf{H} \end{aligned}$$

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Restriction to Finitary HITs

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$$\begin{aligned} (x_1 : A_1) &\rightarrow \cdots \rightarrow (x_m : A_m(x_1, \dots, x_{m-1})) \\ &\rightarrow (B_1(x_1, \dots, x_m) \rightarrow \mathbf{H}) \rightarrow \cdots \\ &\rightarrow (B_n(x_1, \dots, x_m) \rightarrow \mathbf{H}) \rightarrow \mathbf{H} \end{aligned}$$

If B_j is empty \rightarrow **finitary inductive definition.**



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$$\begin{aligned} c_0 : (x_1 : A_1) &\rightarrow \dots \rightarrow (x_m : A_m(x_1, \dots, x_{m-1})) \\ &\rightarrow \mathbf{H} \rightarrow \dots \rightarrow \mathbf{H} \rightarrow \mathbf{H} \end{aligned}$$



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$$\begin{aligned}c_1 &: (x_1 : B_1) \rightarrow \cdots \rightarrow (x_n : B_n(x_1, \dots, x_n)) \\ &\rightarrow (y_1 : \mathbf{H}) \rightarrow \cdots \rightarrow (y_{n'} : \mathbf{H}) \\ &\rightarrow p_1(x_1, \dots, x_n, y_1, \dots, y_{n'}) =_{\mathbf{H}} q_1(x_1, \dots, x_n, y_1, \dots, y_{n'}) \\ &\vdots \\ &\rightarrow p_{n''}(x_1, \dots, x_n, y_1, \dots, y_{n'}) =_{\mathbf{H}} q_{n''}(x_1, \dots, x_n, y_1, \dots, y_{n'}) \\ &\rightarrow p'(x_1, \dots, x_n, y_1, \dots, y_{n'}) =_{\mathbf{H}} q'(x_1, \dots, x_n, y_1, \dots, y_{n'})\end{aligned}$$

- $y_j : \mathbf{H}$ is an **inductive premise**;
- $p ::= y \mid c_0(a_1, \dots, a_m, p_1, \dots, p_k)$ - syntax for **point constructor patterns**



Simplified Form for Point and Path Constructors

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One point constructor with $m = 1$:

$$c_0 : A \rightarrow \mathbf{H} \rightarrow \mathbf{H}$$

One path constructor with $n = n' = n'' = 1$:

$$\begin{aligned} c_1 : (x : B) \rightarrow (y : \mathbf{H}) \rightarrow p(x, y) =_{\mathbf{H}} q(x, y) \\ \rightarrow p'(x, y) =_{\mathbf{H}} q'(x, y) \end{aligned}$$



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Elimination and equality rules

Point assumption

$$\tilde{c}_0 : (x : A) \rightarrow (y : A) \rightarrow C(y) \rightarrow C(c_0(x, y))$$

Path assumption

$$\tilde{c}_1 : (x : B) \rightarrow (y : \mathbf{H}) \rightarrow (\tilde{y} : C(y)) \rightarrow (z : p =_{\mathbf{H}} q) \rightarrow$$
$$T_0(p) =_z^C T_0(q) \rightarrow T_0(p') =_{c_1(x, y, z)}^C T_0(q')$$

Result: a function $f : (x : \mathbf{H}) \rightarrow C(x)$.

Equality rules

$$f(c_0(x, y)) = \tilde{c}_0(x, y, f(y))$$

$$\mathbf{apd}_f(c_1(x, y, z)) = \tilde{c}_1(x, y, f(y), z, \mathbf{apd}_f(z))$$

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Elimination and equality rules

Point assumption

$$\tilde{c}_0 : (x : A) \rightarrow (y : A) \rightarrow C(y) \rightarrow C(c_0(x, y))$$

Path assumption

$$\tilde{c}_1 : (x : B) \rightarrow (y : \mathbf{H}) \rightarrow (\tilde{y} : C(y)) \rightarrow (z : p =_{\mathbf{H}} q) \rightarrow \\ T_0(p) =_z^C T_0(q) \rightarrow T_0(p') =_{c_1(x, y, z)}^C T_0(q')$$

Result: a function $f : (x : \mathbf{H}) \rightarrow C(x)$.

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The lifting function: example

- The lifting of $p : \mathbf{H}$ is denoted $T_0(p) : C(p)$
- The idea is that $T_0(p) = f(p)$ for the resulting function f

Example (\tilde{K}_{conv}):

$$T_0(app(app(K, x), y)) = a\tilde{p}p(app(K, x), a\tilde{p}p(K, \tilde{K}, x, \tilde{x}), y, \tilde{y})$$
$$T_0(x) = \tilde{x}$$

This lifting function is defined by:

$$T_0(x) = \tilde{x}, T_0(y) = \tilde{y}, T_0(K) = \tilde{K}, T_0(S) = \tilde{S} \text{ and}$$
$$T_0(app(t, t')) = a\tilde{p}p(t, T_0(t), t', T_0(t'))$$

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$$T_0(\text{app}(\text{app}(K, x), y)) = \tilde{\text{app}}(\text{app}(K, x), \tilde{\text{app}}(K, \tilde{K}, x, \tilde{x}), y, \tilde{y})$$
$$T_0(x) = \tilde{x}$$

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$$T_0(\text{app}(t, t')) = \tilde{\text{app}}(t, T_0(t), t', T_0(t'))$$

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$$T_0(\text{app}(t, t')) = \text{app}(t, T_0(t), t', T_0(t'))$$

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The lifting function: general

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General definition of $(T_0(p(x, y)) : C(p(x, y)))$:

$$T_0(y) = \tilde{y}$$

$$T_0(c_0(a, p)) = \tilde{c}_0(a, p, T_0(p))$$

Hence, $x : B, y : \mathbf{H}, \tilde{y} : C(y) \vdash T_0(p(x, y)) : C(p(x, y))$ and
 $T_0(p)(x, y, f(y)) = f(p(x, y))$



The lifting function: general

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 $T_0(p)(x, y, f(y)) = f(p(x, y))$



Example: The circle again

```
Inductive circle : Type :=  
| base : circle  
| loop : base == base.
```

$$\frac{b\tilde{a}se : C(\text{base}) \quad l\tilde{o}op : T_0(\text{base}) =_{loop}^C T_0(\text{base})}{f : (x : \text{circle}) \rightarrow C(x)}$$

- $f(\text{base}) = b\tilde{a}se$
- $apdf(loop) = l\tilde{o}op$

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Example: Natlist

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```
Inductive Natlist: Type :=
| Nil : Natlist
| Cons : nat → Natlist → Natlist
| NilEq: Nil = Nil
| ConsEq : forall n1, n2 : nat →
           forall l1, l2 : Natlist →
           n1 = n2 → l1 = l2 →
           Cons(n1, l1) = Cons(n2, l2)
```



Example: Natlist (elimination rule)

Point constructors:

$$\tilde{Nil} : C(Nil)$$

$$\tilde{Cons} : (n : nat) \rightarrow (l : Natlist) \rightarrow C(l) \rightarrow C(cons(n, l))$$

Path constructors:

$$nil\tilde{Eq} : T_0(Nil) =_{C_{NilEq}} T_0(Nil)$$

$$\begin{aligned} \tilde{ConsEq} : & (n1, n2 : nat) \rightarrow (l1, l2 : Natlist) \rightarrow (\tilde{l1} : C(l1)) \\ & \rightarrow (\tilde{l2} : C(l2)) \rightarrow (x : n1 =_{Natlist} n2) \rightarrow (y : l1 =_{Natlist} l2) \\ & T_0(n1) =_x^C T_0(n2) \rightarrow T_0(l1) =_y^C T_0(l2) \rightarrow \\ & T_0(Cons(n1, l1)) =_{ConsEq(n1, n2, l1, l2, x, y)}^C T_0(Cons(n2, l2)) \end{aligned}$$

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Example: Natlist (equality rule)

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$$f(\text{Nil}) = \tilde{\text{Nil}}$$

$$f(\text{Cons}(n, l)) = \tilde{\text{Cons}}(n, l, f(l))$$

$$\mathbf{apd}_f(\text{NilEq}) = \text{NilEq}$$

$$\mathbf{apd}_f(\text{ConsEq}(n_1, n_2, l_1, l_2, x, y)) = \tilde{\text{ConsEq}}(n_1, n_2, l_1, l_2, \\ f(l_1), f(l_2), z_1, z_2, \\ \mathbf{apd}_f(z_1), \mathbf{apd}_f(z_2)).$$



End of presentation

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