

# Exercises Model-based Reasoning

## Exercise 1

Consider the diagnostic problem DP with system description SD, which contains the following generic descriptions of components:

$$\forall x(\text{ANDG}(x) \rightarrow \text{and}(\text{in}_1(x), \text{in}_2(x)) = \text{out}(x))$$

$$\forall x(\text{ORG}(x) \rightarrow \text{or}(\text{in}_1(x), \text{in}_2(x)) = \text{out}(x))$$

$$\forall x((\text{INV}(x) \rightarrow \neg(\text{in}(x) = \text{out}(x)))$$

- Show how this system description should be adapted to employ it for consistency-based diagnosis.
- What is the role of the system description in model-based diagnosis?
- Design a circuit consisting of two ANDG components, one INV component, and one ORG component, with appropriate wiring, inputs and outputs.
- Give an example showing how this circuits converts inputs into outputs, i.e., give a set of observations OBS that match the expected, normal behaviour of the circuit.
- Add to SD (a) logical formula(s) describing the behaviour of a wire(s). You may need more than one formula; try to understand why.

## Exercise 2

The concept of hitting sets underlies the algorithm of consistency-based diagnosis, i.e., to determine diagnoses for a diagnostic problem. As explained at the lecture, diagnoses for a system are exactly the (minimal) hitting sets of the system's conflict sets. In this exercise we intend to take a closer look at determining hitting sets from a set of conflict sets. Now, let  $F = \{\{5, 3, 4\}, \{2, 4, 6\}, \{1, 3, 7\}, \{3\}\}$  be a set of sets.

- Read the slides on hitting sets and in particular the definition of the notion of hitting set.  
Now, determine all the hitting sets of the given set  $F$ .
- Which of these hitting sets are minimal (by minimal we mean minimal according to the subset relationship  $\subseteq$ )?
- Finally, build a hitting-set tree  $T = (V, E, L_V, l_E)$ , with set of nodes  $V$  and edges (branches)  $E \subseteq V \times V$ , and two label functions:

$$l_V : V \rightarrow F \cup \{\checkmark\},$$

which labels each node in  $V$  with a set  $S$  from the set  $F$  or a tick ( $\checkmark$ ), and

$$l_E : E \rightarrow \bigcup_{S \in F} S,$$

which labels each edge in  $E$  with an element coming from an element in a set  $S \in F$ . Note that there are multiple ways to do this.

### Exercise 3

Consider the schema of a circuit shown in the following figure:



where

- $I$  implements an inverter,  $INV(I)$ , with the following behaviour:

$$\forall x((INV(x) \wedge \neg Ab(x)) \rightarrow (out(x) = 1 \leftrightarrow in(x) = 0))$$

(Note the difference in specification with the inverter in Exercise 1; is there a major difference between the two specifications?)

- $O$  implements a logical OR gate,  $ORG(O)$ , with the following behaviour:

$$\forall x((ORG(x) \wedge \neg Ab(x)) \rightarrow out(x) = or(in_1(x), in_2(x)))$$

The following observations have been made  $OBS = \{i_1 = 0, i_2 = 0, o = 0\}$ .

- Give the system specification  $SYS$  of the circuit.
- Determine the diagnoses according to the theory of consistency-based diagnosis.
- Determine all conflict sets, and next all minimal hitting sets. Compare your results with those to question 3.b.

### Exercise 4

- Consider the diagnostic problem  $DP = (SYS, OBS)$  in the theory of consistency-based diagnosis, with:

- $SYS = (SD, COMPS)$  is the system specification with

– system description

$$\begin{aligned} SD = \{ & \forall x((ANDG(x) \wedge \neg Ab(x)) \rightarrow (and(in(1, x), in(2, x)) = out(x))), \\ & \forall x((ORG(x) \wedge \neg Ab(x)) \rightarrow (or(in(1, x), in(2, x)) = out(x))), \\ & in(2, O_1) = in(2, O_2), \\ & in(2, A_2) = in(2, A_1), \\ & out(O_1) = in(1, A_1), \\ & out(O_1) = in(1, A_2), \\ & out(A_2) = in(1, O_2), \\ & ORG(O_1), ORG(O_2), ANDG(A_1), ANDG(A_2)\}; \end{aligned}$$

–  $COMPS = \{A_1, A_2, O_1, O_2\}$ ;

- $OBS = \{in(1, O_1) = 1, in(2, O_1) = 0, in(2, A_2) = 1, out(A_1) = 0, out(O_2) = 0\}$  is the set of observations

Determine the set of conflict sets of  $DP$ . Which conflict sets are minimal? Determine the set of diagnoses with the hitting-set algorithm.

- Give an example of an optimisation of the hitting-set algorithm that reduces the size of the hitting-set tree.

### Exercise 5

Consistency-based diagnosis is frequently characterised as a form of non-monotonic reasoning. Give an simple example showing that this characterisation is right.

### Exercise 6

- a. Describe a problem situation where consistency-based diagnosis is the only possible diagnostic method. Explain your answer.
- b. Formalisation of the notion of causality in abductive diagnosis is usually done by means of logical implication  $\rightarrow$ . Which properties of logical implication fit the intuitive meaning of causality well? Which property of logical implication does not fit?

### Exercise 7

Consider the causal specification  $\Sigma = (\Delta, \Phi, \mathcal{R})$ , where

- $\Delta = \{d_1, d_2, d_3, \alpha_1, \alpha_2\}$  is a set of defects ( $d_1, d_2, d_3$ ) and assumption literals ( $\alpha_1, \alpha_2$ );
- $\Phi = \{f_1, f_2, f_3\}$  is a set of observables;
- $\mathcal{R} = \{d_1 \wedge \alpha_1 \rightarrow d_2,$   
 $d_1 \rightarrow f_1,$   
 $d_2 \wedge \alpha_2 \rightarrow f_2,$   
 $d_2 \wedge d_3 \rightarrow f_3\}$

is a model of abnormal behaviour.

Furthermore, let  $\mathcal{P} = (\Sigma, E)$  be a diagnostic problem, with  $E = \{f_1, f_3\}$  a set of observed facts.

- a. Determine all abductive diagnoses for  $\mathcal{P}$ .
- b. Determine subsequently the solution disjunction that follows from the predicate completion of  $\mathcal{R}$  and the set of observed facts  $E$  under the assumption that all elements in  $\Delta$ , with the exception of  $d_2$ , are abducible.
- c. Finally, discuss the relationship between the solution formula and the abductive diagnoses for  $\mathcal{P}$ .