

# Learning from soft evidence

A mathematical view on Jeffrey's rule and Pearl's rule

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# Overview

- Updating beliefs
- Soft evidence
- Mathematical framework
- Jeffrey's rule and Pearl's rule
- Example
- Properties of Jeffrey's rule and Pearl's rule
- Open questions and conclusion



# Updating beliefs

- We form beliefs, e.g. about the color of a car.
- Formally, a belief is a probability distribution.
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- We form beliefs, e.g. about the color of a car.
- Formally, a belief is a probability distribution.
- When learning new evidence, we update our beliefs.
- Hard evidence: A statement that some event happened with certainty, e.g. 'The car is red.'
- Soft evidence: A statement that some event happened with some uncertainty, e.g. 'I'm 70% sure the car is red.'

# Soft evidence

- Soft evidence: A statement that some event happened with some uncertainty, e.g. 'I'm 70% sure the car is red.'
- Two ways to deal with soft evidence, giving very different results:
  - Jeffrey's rule (1965)
  - Pearl's rule (1988)
- Main challenges:
  - Common mathematical framework
  - When to use which rule?
- Studied by Jacobs (2019) and Jacobs (2021).



# States and channels

- State  $\omega \in \mathcal{D}(X)$ : probability distribution over  $X$

$$\omega = r_1|x_1\rangle + \dots + r_n|x_n\rangle$$

where  $x_i \in X$ ,  $r_i \in [0, 1]$  and  $\sum_i r_i = 1$ .

We also write  $\omega(x_i) = r_i$ .



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- Channel: A function  $c: X \rightarrow \mathcal{D}(Y)$ .  
We also write  $c: X \dashrightarrow Y$ .
- State transformation: given  $\omega \in \mathcal{D}(X)$  and  $c: X \dashrightarrow Y$ .  
The predicted state  $c \gg \omega \in \mathcal{D}(Y)$  is given by

$$(c \gg \omega)(y) = \sum_x \omega(x) \cdot c(x)(y).$$

This is the ‘law of total probability’.



## Example: burglar and alarm

Each night, there is a 0.1% chance that a burglar will break into my house. If a burglar is in my house, the alarm goes off with 80% probability. If there is no burglar, the alarm goes off with a 1% probability.



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- Let  $X = \{b, b^\perp\}$ : there is a burglar ( $b$ ) or not ( $b^\perp$ ).
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- State:  $\omega = 0.001|b\rangle + 0.999|b^\perp\rangle \in \mathcal{D}(X)$ .

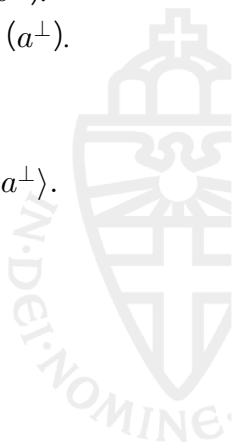
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- Channel:  $c: X \rightarrow Y$ , 
$$\begin{cases} c(b) = 0.8|a\rangle + 0.2|a^\perp\rangle \\ c(b^\perp) = 0.01|a\rangle + 0.99|a^\perp\rangle. \end{cases}$$
- Gives the probability distribution over the states of the alarm based on whether or not there is a burglar.

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- Predicted state:

$$\begin{aligned} (c \gg \omega)(a) &= \omega(b)c(b)(a) + \omega(b^\perp)c(b^\perp)(a) \\ &= 0.001 \cdot 0.8 + 0.999 \cdot 0.01 = 0.01079. \end{aligned}$$

Similarly,  $(c \gg \omega)(a^\perp) = 0.98921$ .

So  $c \gg \omega = 0.01079|a\rangle + 0.98921|a^\perp\rangle \in \mathcal{D}(Y)$ .

# Fuzzy predicates

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$$\sigma \models p = \sum_x \sigma(x) \cdot p(x).$$

This can also be seen as an ‘expected value’.





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This can also be seen as an ‘expected value’.

- Updated state  $\sigma|_p \in \mathcal{D}(X)$ , given that predicate  $p$  holds:

$$\sigma|_p(x) = \frac{\sigma(x) \cdot p(x)}{\sigma \models p}.$$

# Predicate transformation

- Predicates can also be transformed over a channel.
- In the opposite direction: given a channel  $c: X \multimap Y$  and a predicate  $q: Y \rightarrow [0, 1]$ , define a predicate  $c \ll q: X \rightarrow [0, 1]$ :

$$(c \ll q)(x) = \sum_y c(x)(y) \cdot q(y).$$



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## Lemma

Let  $c: X \multimap Y$  be a channel, let  $q: Y \rightarrow [0, 1]$  be a predicate and let  $\omega \in \mathcal{D}(X)$ . Then  $(c \gg \omega) \models q = \omega \models (c \ll q)$ .

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*Proof.*

$$(c \gg \omega) \models q = \sum_y (c \gg \omega)(y) q(y)$$



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$$\begin{aligned}(c \gg \omega) \models q &= \sum_y (c \gg \omega)(y) q(y) \\ &= \sum_y \left( \sum_x \omega(x) \cdot c(x)(y) \right) q(y)\end{aligned}$$

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Let  $c: X \multimap Y$  be a channel, let  $q: Y \rightarrow [0, 1]$  be a predicate and let  $\omega \in \mathcal{D}(X)$ . Then  $(c \gg \omega) \vDash q = \omega \vDash (c \ll q)$ .

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# Bayesian inversion

- Given a (prior) state  $\sigma \in \mathcal{D}(X)$  and a channel  $c: X \multimap Y$ , it is possible to define an inverted channel  $c_\sigma^\dagger: Y \multimap X$ :

$$c_\sigma^\dagger(y) = \sum_x \frac{\sigma(x) \cdot c(x)(y)}{(c \gg \sigma)(y)} |x\rangle.$$

- Let  $\mathbf{1}_y: Y \rightarrow [0, 1]$  be a predicate on satisfying

$$\mathbf{1}_y(y') = \begin{cases} 1 & \text{if } y' = y \\ 0 & \text{otherwise.} \end{cases}$$

Then  $c_\sigma^\dagger(y) = \sigma|_{c \ll \mathbf{1}_y}$ .

## Example: burglar and alarm

- Let  $X = \{b, b^\perp\}$  and  $Y = \{a, a^\perp\}$ .
- State:  $\omega = 0.001|b\rangle + 0.999|b^\perp\rangle \in \mathcal{D}(X)$ .
- Channel:  $c: X \rightarrow Y$ ,  $\begin{cases} c(b) = 0.8|a\rangle + 0.2|a^\perp\rangle \\ c(b^\perp) = 0.01|a\rangle + 0.99|a^\perp\rangle. \end{cases}$
- Predicted state:  $c \gg \omega = 0.01079|a\rangle + 0.98921|a^\perp\rangle \in \mathcal{D}(Y)$ .

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- Predicted state:  $c \gg \omega = 0.01079|a\rangle + 0.98921|a^\perp\rangle \in \mathcal{D}(Y)$ .
- Inverted channel  $c_\omega^\dagger: Y \rightarrow X$ :

$$\begin{aligned} c_\omega^\dagger(a) &= \frac{\omega(b) \cdot c(b)(a)}{(c \gg \omega)(a)} |b\rangle + \frac{\omega(b^\perp) \cdot c(b^\perp)(a)}{(c \gg \omega)(a)} |b^\perp\rangle \\ &= \frac{0.001 \cdot 0.8}{0.01079} |b\rangle + \frac{0.999 \cdot 0.01}{0.01079} |b^\perp\rangle \\ &\approx 0.0741|b\rangle + 0.9259|b^\perp\rangle. \end{aligned}$$

Similarly,  $c_\omega^\dagger(a^\perp) \approx 0.0002|b\rangle + 0.9998|b^\perp\rangle$ .

# Jeffrey's rule and Pearl's rule

- Let  $c: X \rightarrow Y$  be a channel with prior state  $\sigma \in \mathcal{D}(X)$ .
- For Jeffrey's rule, consider evidence in the form of a state  $\rho \in \mathcal{D}(Y)$ . Then Jeffrey's update is given by

$$c_{\sigma}^{\dagger} \gg \rho \in \mathcal{D}(X).$$



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- For Pearl's rule, consider evidence in the form of a predicate  $q: Y \rightarrow [0, 1]$ . Then Pearl's update is given by

$$\sigma|_{c \ll q} \in \mathcal{D}(X).$$

# Interpretation of Jeffrey's and Pearl's rule

- Jeffrey's rule assumes that evidence is of the type 'all things considered', i.e. taking into account other evidence.
- Jeffrey's rule can be interpreted as a correction.
- Pearl's rule assumes that evidence is of the type 'nothing else considered', i.e. not taking into account other evidence.
- Pearl's rule can be interpreted as an improvement.

## Example: soft evidence

Around 3% of the cars in a city is red. One day, a car drives way too fast through the city center. The police asks for the car color. A witness: I'm 70% sure the car is red.

- Prior probability:  $\Pr(r) = \frac{3}{100}$  and  $\Pr(r^\perp) = \frac{97}{100}$ .
- Let  $X = \{r, r^\perp\}$  and let  $\omega = \frac{3}{100}|r\rangle + \frac{97}{100}|r^\perp\rangle \in \mathcal{D}(X)$ .
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- Pearl's rule: predicate  $q: X \rightarrow [0, 1]$  defined by  $q(r) = \frac{7}{10}$  and  $q(r^\perp) = \frac{3}{10}$ . To compute:  $\omega|_{c \ll q}$ .



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- We have

$$(c \ll q)(x) = \sum_y c(x)(y) \cdot q(y) = \sum_y \delta_{xy} \cdot q(y) = q(x),$$

so  $c \ll q = q$ .

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- So  $\omega|_{c \ll q} = \frac{21}{312}|r\rangle + \frac{291}{312}|r^\perp\rangle \in \mathcal{D}(X)$ .

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To compute:  $c_\omega^\dagger \gg \rho$ .
- We have  $c \gg \omega = \omega$  and hence

$$c_\omega^\dagger(y) = \sum_x \frac{\omega(x)c(x)(y)}{(c \gg \omega)(y)} |x\rangle = \frac{\omega(y)}{(c \gg \omega)(y)} |y\rangle = 1|y\rangle = c(y),$$

so  $c_\omega^\dagger = c$ .

## Example: soft evidence

- Prior probability:  $\Pr(r) = \frac{3}{100}$  and  $\Pr(r^\perp) = \frac{97}{100}$ .
- Let  $X = \{r, r^\perp\}$  and let  $\omega = \frac{3}{100}|r\rangle + \frac{97}{100}|r^\perp\rangle \in \mathcal{D}(X)$ .
- Channel:  $c: X \rightarrow X$  defined by  $c(x) = 1|x\rangle$ .
- Jeffrey's rule: state  $\rho \in \mathcal{D}(X)$  defined by  $\rho = \frac{7}{10}|r\rangle + \frac{3}{10}|r^\perp\rangle$ .  
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To compute:  $c_\omega^\dagger \gg \rho$ .
- We have  $c_\omega^\dagger = c$ .
- We have

$$(c_\omega^\dagger \gg \rho)(y) = \sum_x \rho(x) c_\omega^\dagger(x)(y) = \sum_x \rho(x) \delta_{xy} = \rho(y),$$

$$\text{so } c_\omega^\dagger \gg \rho = \rho = \frac{7}{10}|r\rangle + \frac{3}{10}|r^\perp\rangle \in \mathcal{D}(X).$$

## Example: soft evidence

Around 3% of the cars in a city is red. One day, a car drives way too fast through the city center. The police asks for the car color. A witness: I'm 70% sure the car is red.

- Pearl's rule:  $\frac{21}{312}|r\rangle + \frac{291}{312}|r^\perp\rangle \in \mathcal{D}(X)$ .
- Jeffrey's rule:  $\frac{7}{10}|r\rangle + \frac{3}{10}|r^\perp\rangle \in \mathcal{D}(X)$ .
- Pearl's rule: although the witness is 70% sure, it is much more likely that the car was not red.
- Jeffrey's rule: the witness is 70% sure taking into account there are very few red cars.
- In general the inverted channel  $c_\omega^\dagger$  and hence the result of Jeffrey's rule actually depends on the prior.

# Applications of Jeffrey's rule do not commute

- In the red car example, we saw that  $c_w^\dagger \gg \rho = \rho$ .
- Now consider two witnesses with states  $\rho_1$  and  $\rho_2$ .
- First witness 1, then witness 2:  $c_w^\dagger \gg \rho_1 = \rho_1$ , then  $c_{\rho_1}^\dagger \gg \rho_2 = \rho_2$ . So final updated state is  $\rho_2$ .
- First witness 2, then witness 1: Final updated state is  $\rho_1$ .
- If witness 1's update is done first, witness 2 needs to take into account witness 1's testimony.

# Applications of Jeffrey's rule do not commute

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- First witness 1, then witness 2:  $c_{\omega}^{\dagger} \gg \rho_1 = \rho_1$ , then  $c_{\rho_1}^{\dagger} \gg \rho_2 = \rho_2$ . So final updated state is  $\rho_2$ .
- First witness 2, then witness 1: Final updated state is  $\rho_1$ .
- If witness 1's update is done first, witness 2 needs to take into account witness 1's testimony.
- So applications of Jeffrey's rule do not commute.
- Applications of Pearl's rule do commute.

# Improvement and correction without effect

- When using Pearl's rule with a uniform likelihood, the beliefs do not change, i.e. improving with no information has no effect.
- When using Jeffrey's rule with the current belief, the beliefs do not change, i.e. correcting beliefs to the current belief has no effect.



# Pearl's rule increases validity

## Theorem

Let  $c: X \multimap Y$  be a channel with prior state  $\sigma \in \mathcal{D}(X)$  and let  $q: Y \rightarrow [0, 1]$  be a predicate. Let  $\sigma_P = \sigma|_{c \ll q}$  denotes Pearl's update. Pearl's rule increases validity:

$$(c \gg \sigma_P) \vDash q \geq (c \gg \sigma) \vDash q.$$

# Pearl's rule increases validity

## Lemma

Let  $\omega \in \mathcal{D}(X)$  be a state and let  $p: X \rightarrow [0, 1]$  be a predicate. Assume that  $\omega \vDash p$  is nonzero. Then

$$\omega|_p \vDash p \geq \omega \vDash p.$$

# Pearl's rule increases validity

## Lemma

Let  $\omega \in \mathcal{D}(X)$  be a state and let  $p: X \rightarrow [0, 1]$  be a predicate. Assume that  $\omega \models p$  is nonzero. Then

$$\omega|_p \models p \geq \omega \models p.$$

*Proof.* Recall that  $\omega \models p = \sum_x \omega(x)p(x)$  and  $\omega|_p(x) = \frac{\omega(x)p(x)}{\omega \models p}$ . Hence,  $\omega|_p \models p = \sum_x \frac{\omega(x)p(x)}{\omega \models p} p(x) = \frac{1}{\omega \models p} \sum_x \omega(x)p(x)^2$ .

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$$\left( \sum_x \omega(x)(p(x))^2 \right) \geq (\omega \models p)^2 = \left( \sum_x \omega(x)p(x) \right)^2.$$

# Pearl's rule increases validity

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Let  $\omega \in \mathcal{D}(X)$  be a state and let  $p: X \rightarrow [0, 1]$  be a predicate. Assume that  $\omega \models p$  is nonzero. Then

$$\omega|_p \models p \geq \omega \models p.$$

*Proof.* The Cauchy-Schwarz inequality states that  $(\sum_i y_i^2) (\sum_i z_i^2) \geq (\sum_i y_i z_i)^2$ . Let  $y_i = \sqrt{\omega(x)}p(x)$  and  $z_i = \sqrt{\omega(x)}$ . Then

$$\left( \sum_x \omega(x)(p(x))^2 \right) \underbrace{\left( \sum_x \omega(x) \right)}_{=1} \geq \left( \sum_x \omega(x)p(x) \right)^2.$$

# Pearl's rule increases validity

## Theorem

Let  $c: X \rightarrow Y$  be a channel with prior state  $\sigma \in \mathcal{D}(X)$  and let  $q: Y \rightarrow [0, 1]$  be a predicate. Let  $\sigma_P = \sigma|_{c \ll q}$  denotes Pearl's update. Pearl's rule increases validity:

$$(c \gg \sigma_P) \vDash q \geq (c \gg \sigma) \vDash q.$$

*Proof.* For any state  $\omega$  we have  $(c \gg \omega) \vDash q = \omega \vDash (c \ll q)$ . By the lemma, it follows that

$$\begin{aligned} (c \gg (\sigma|_{c \ll q})) \vDash q &= \sigma|_{c \ll q} \vDash (c \ll q) \\ &\geq \sigma \vDash (c \ll q) = (c \gg \sigma) \vDash q. \end{aligned}$$

# Jeffrey's rule decreases KL-divergence

## Definition (Kullback-Leibler divergence)

Let  $\omega, \rho \in \mathcal{D}(X)$ . The KL divergence  $D_{KL}(\omega, \rho)$  is defined as

$$D_{KL}(\omega, \rho) = \sum_x \omega(x) \ln \left( \frac{\omega(x)}{\rho(x)} \right).$$

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- $D_{KL}(\omega, \rho) \geq 0$  and  $D_{KL}(\omega, \rho) = 0$  if and only if  $\omega = \rho$ .
- The KL divergence is *not* symmetric, i.e. in general  $D_{KL}(\omega, \rho) \neq D_{KL}(\rho, \omega)$ .



# Jeffrey's rule decreases KL-divergence

## Theorem

Let  $c: X \rightarrow Y$  be a channel with prior state  $\sigma \in \mathcal{D}(X)$ . Assume that  $Y$  is finite and that  $c \gg \sigma$  has full support. Let  $\tau \in \mathcal{D}(Y)$  be an evidence state, and let  $\sigma_J = c_{\sigma}^{\dagger} \gg \tau$  denote Jeffrey's update. Jeffrey's rule decreases divergence:

$$D_{KL}(\tau, c \gg \sigma_J) \leq D_{KL}(\tau, c \gg \sigma).$$

# Open questions

- Are there other measures which always increase or decrease when doing an update according to Pearl's rule or Jeffrey's rule?
- What to do when evidence takes some, but not all other information into account?
- What does soft evidence actually mean?
- Is there a cognitive difference between 'improvement' and 'correction'?

# Conclusion

- Pearl's rule: improvement  
Evidence type: 'nothing else considered'.
- Jeffrey's rule: correction  
Evidence type: 'all things considered'.
- Pearl's rule increases validity of the updating predicate.
- Jeffrey's rule decreases divergence with the updating state.



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